

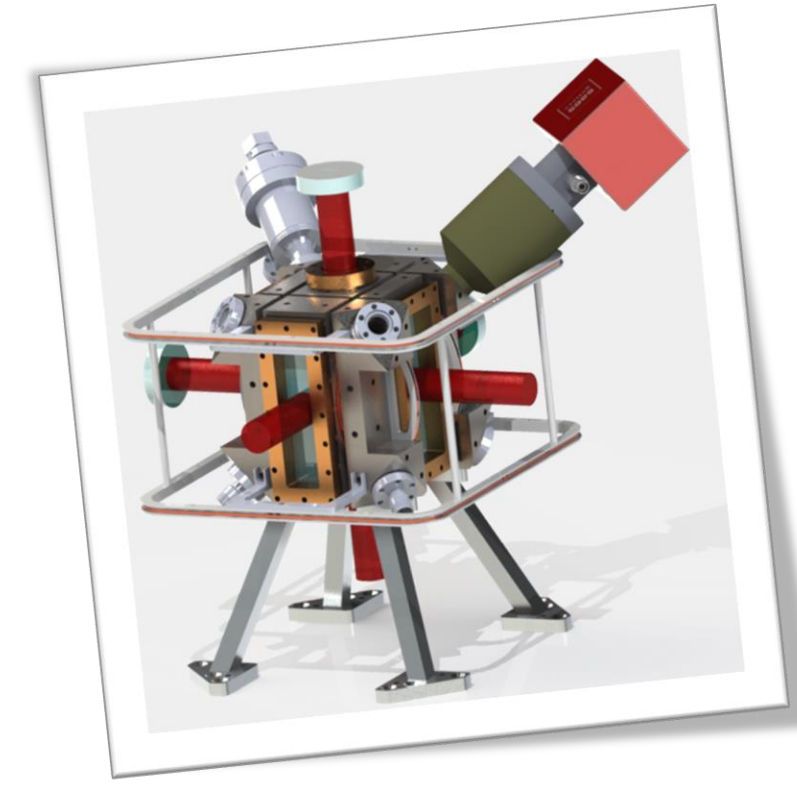
Rotating atom interferometer for onboard quantum inertial sensing

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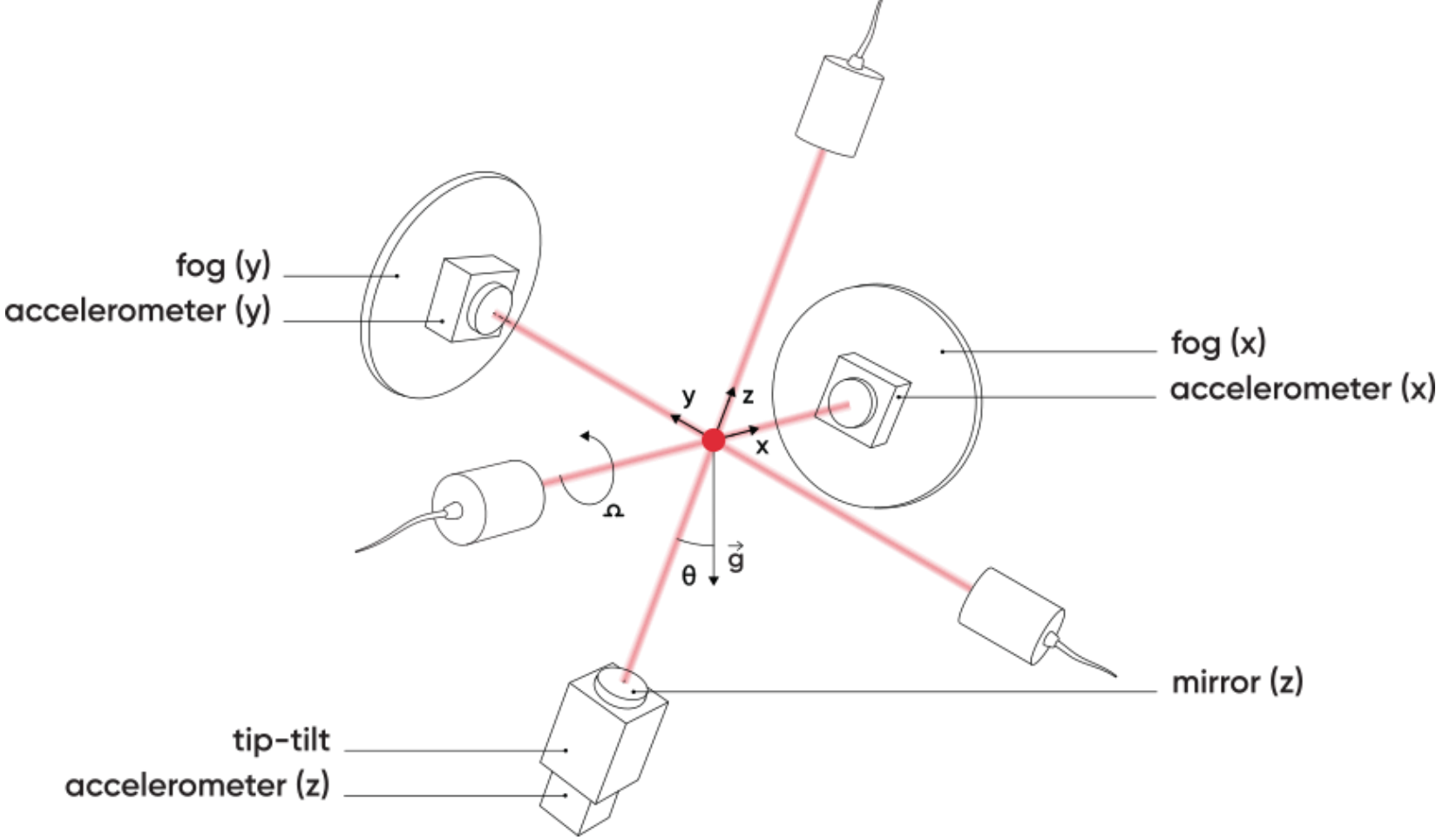
The Joint Laboratory **iXAtom** brings together the expertise of **Exail** and the **LP2N** to build a new generation of onboard, high-end inertial sensors for geophysics and navigation, through the hybridization of classical accelerometers and gyroscopes with quantum inertial sensors based on matter-wave interferometry.



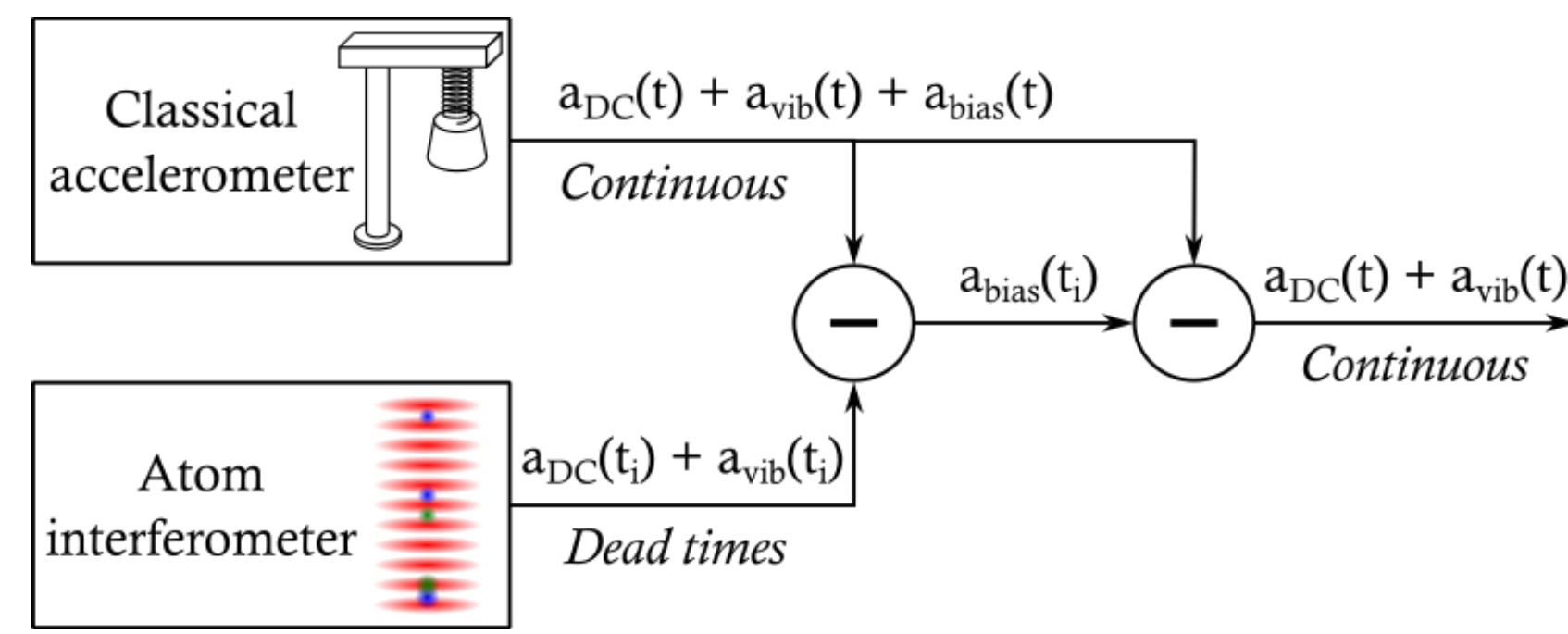
WHAT ARE THE REQUIREMENTS FOR AN ONBOARD INSTRUMENT WORKING IN NOISY ENVIRONMENTS?

A compact, 3-axis sensor head...

- Robust and agile laser source (telecom-band fibered setup, IQ modulator) – *patented* [1]
- Classical accelerometers and gyroscopes



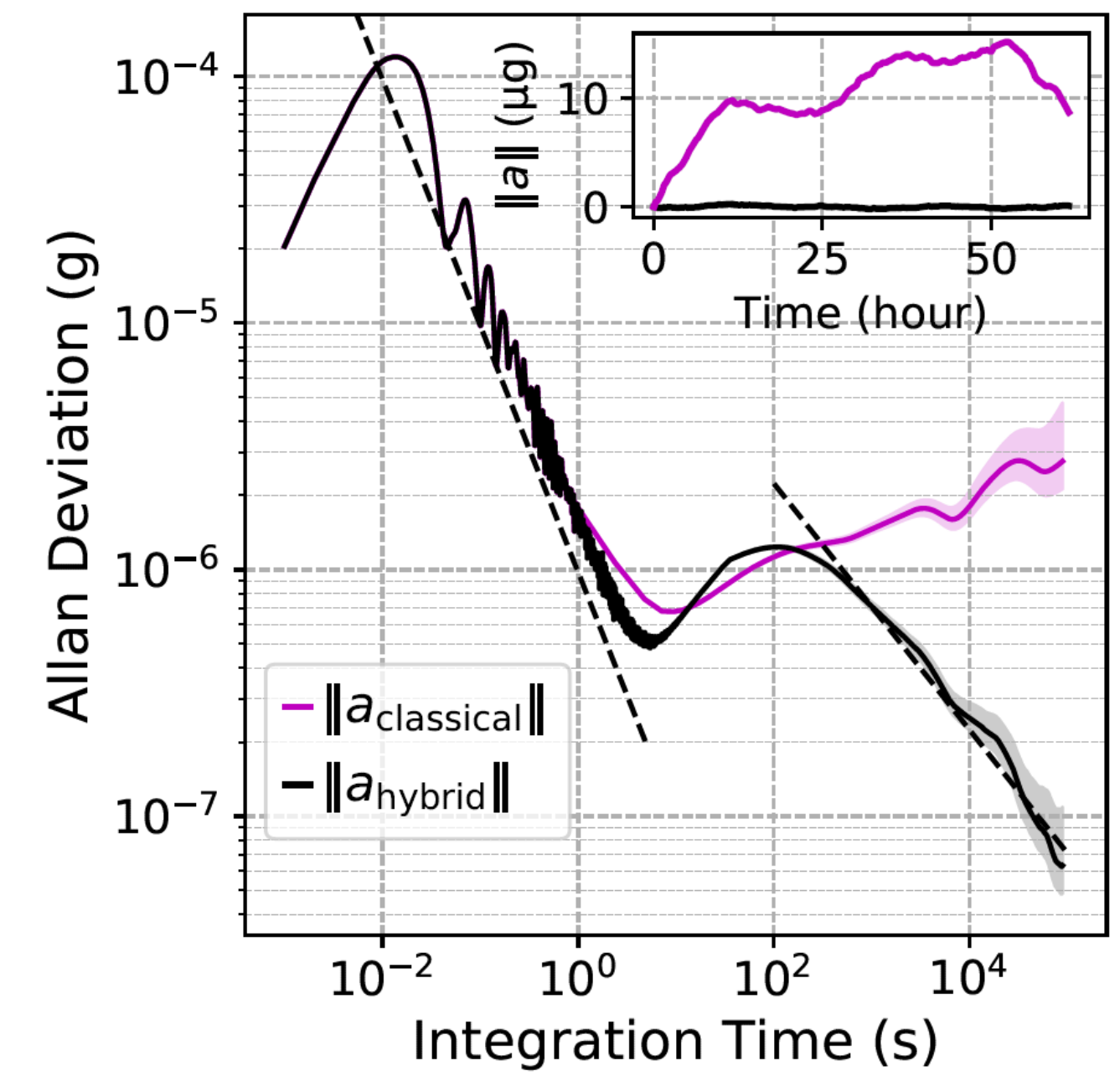
...Working under vibrations...



- Real-time correction of the Doppler frequency shift and vibrations phase noise – *patented* [2]
- Real-time cancellation of the classical bias
- High dynamic range, bias-free, continuous measurement of the acceleration components

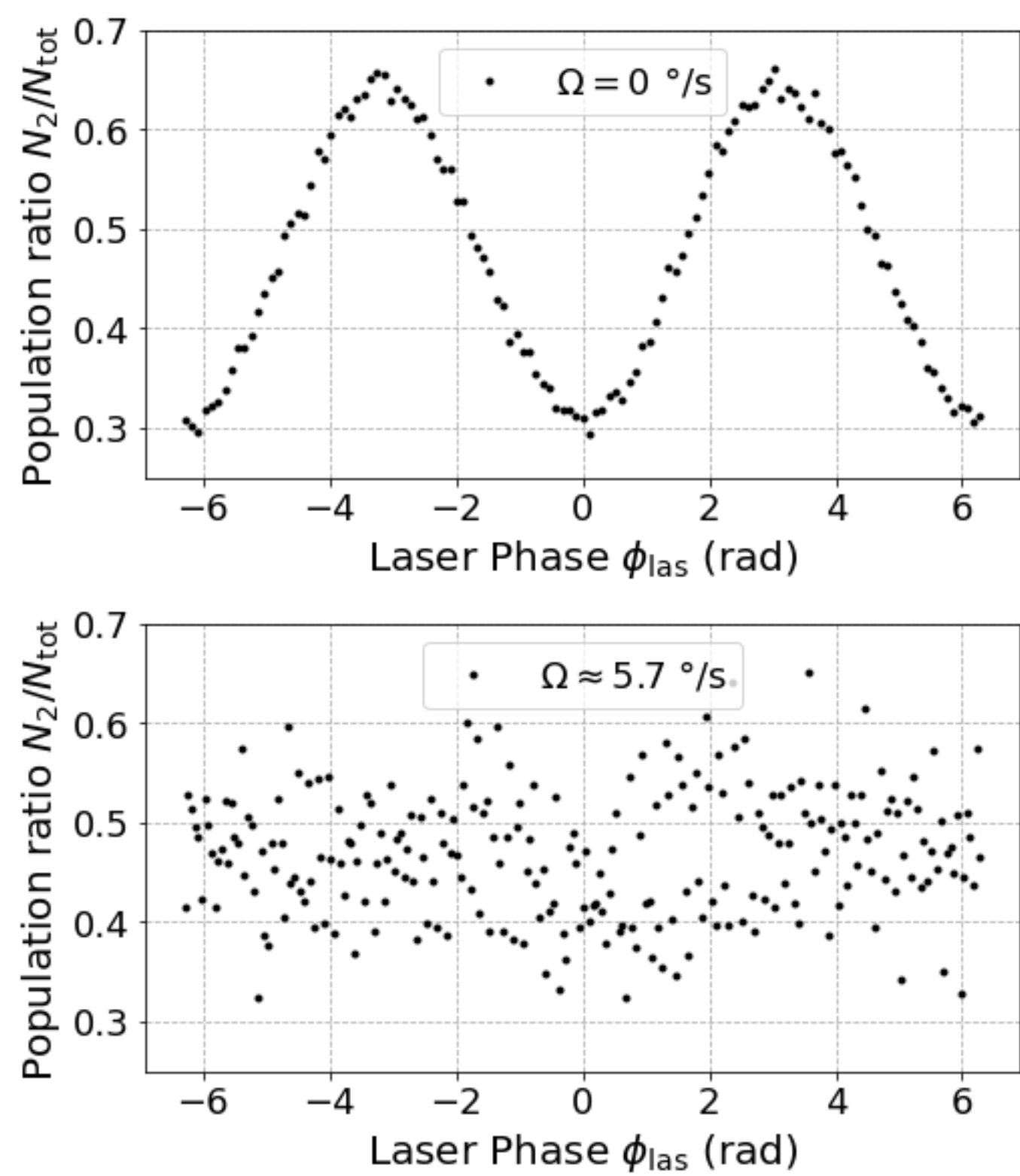
...For improved quasi-static performances [3]

- Bandwidth $BW > 100$ Hz
- Trueness (norm) $|\bar{a} - g| \approx 700$ ng
- Short-term sensitivity $\sigma_a \approx 22$ μg @ 1 s
- Long-term stability $\sigma_a \approx 60$ ng @ 24 h
- 50-fold improvement on the norm of the acceleration vector



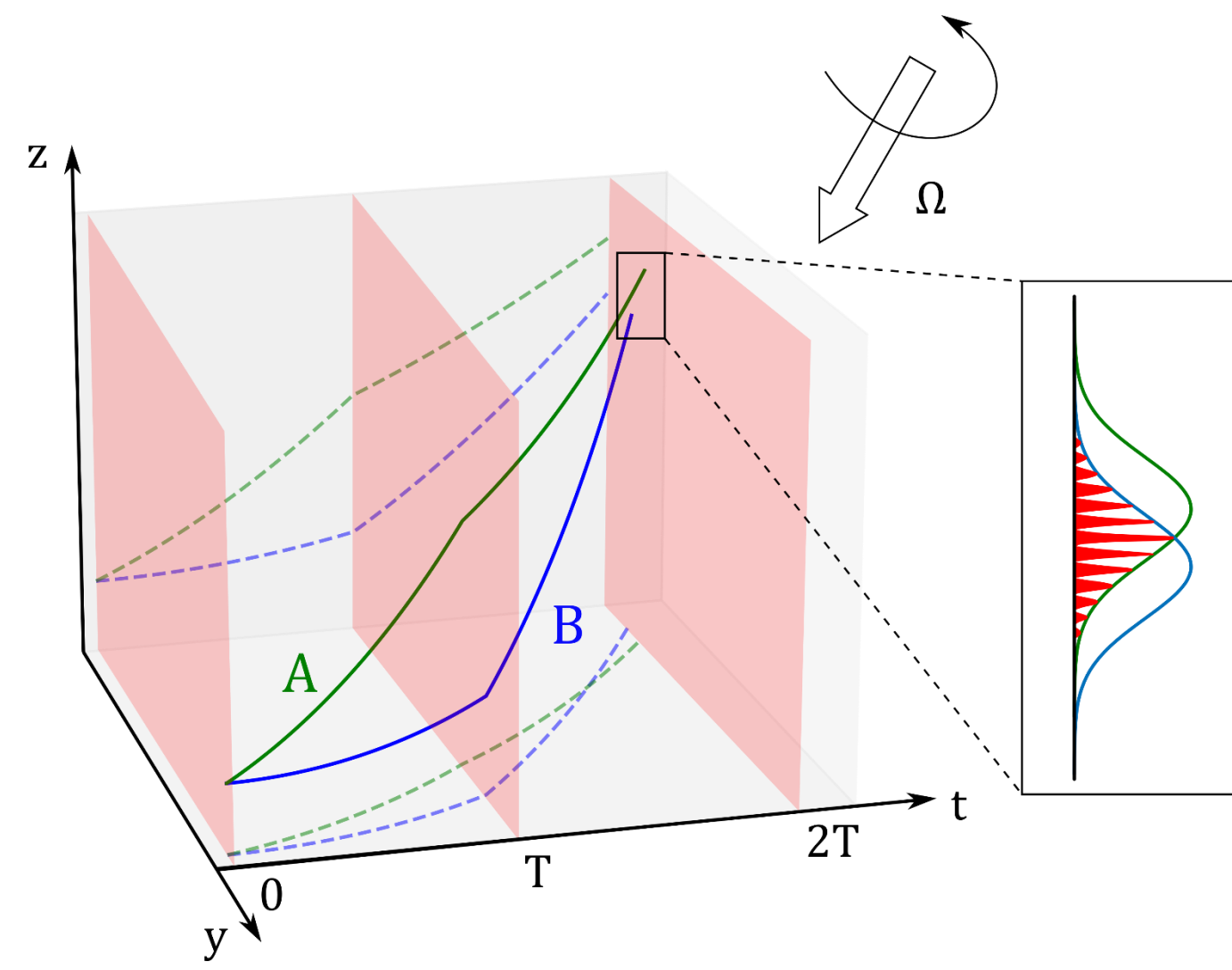
AND WHAT ABOUT ROTATIONS?

Two dramatic effects on the atomic interferences:

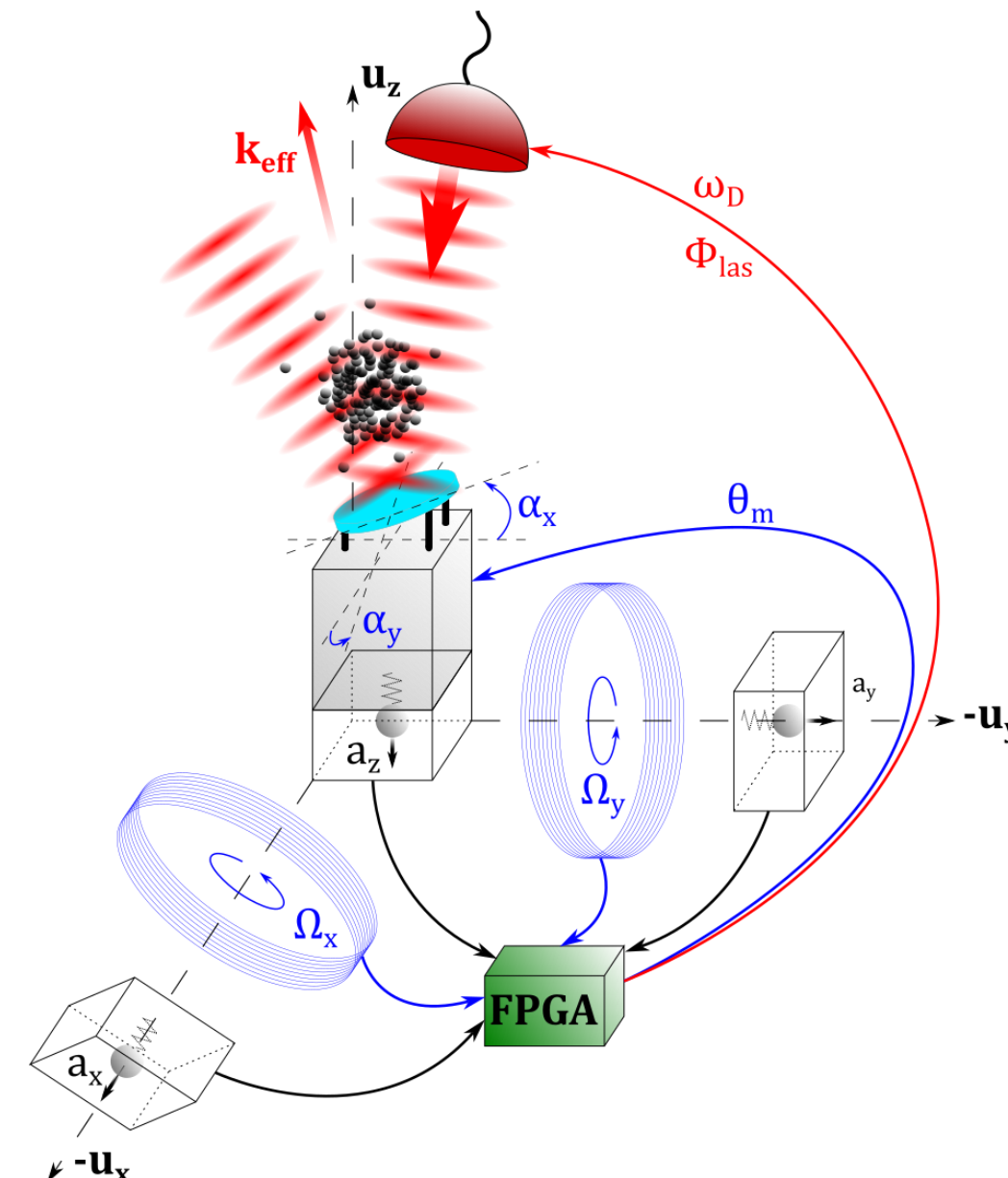


A relative displacement of the atomic wave packets in position and momentum

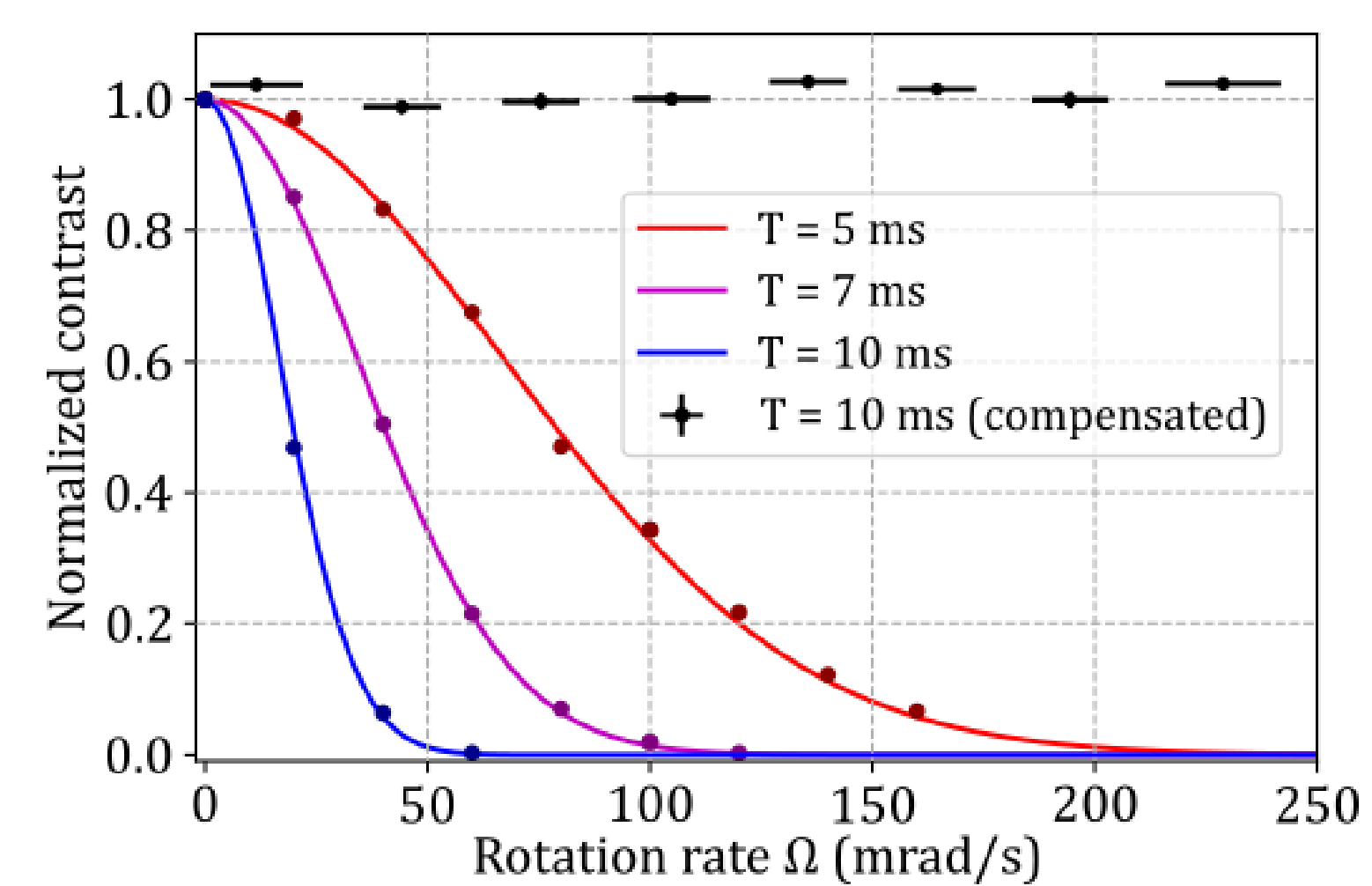
- Problem:** fringe pattern in the density profile at each output port
- For averaging detection systems (photodiodes): overall contrast loss $C(\Omega) \approx C_0 \exp[-(k_{eff} \sigma_v)^2 \Omega^2 T^4]$



- Solution:** real-time stabilization of the effective wave vector's orientation
- Mirror's rotation opposed to that of the chamber (inertial pointing) – *patented*

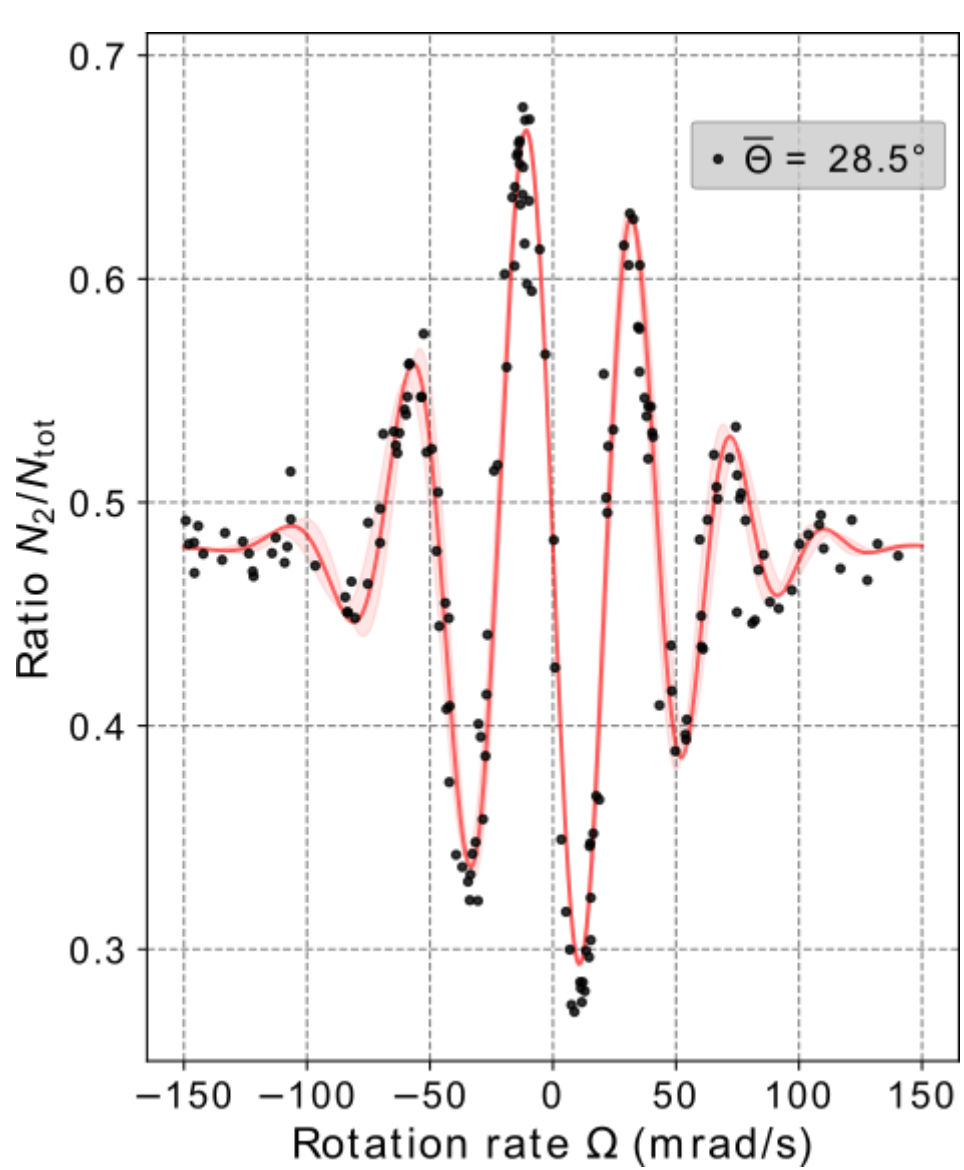
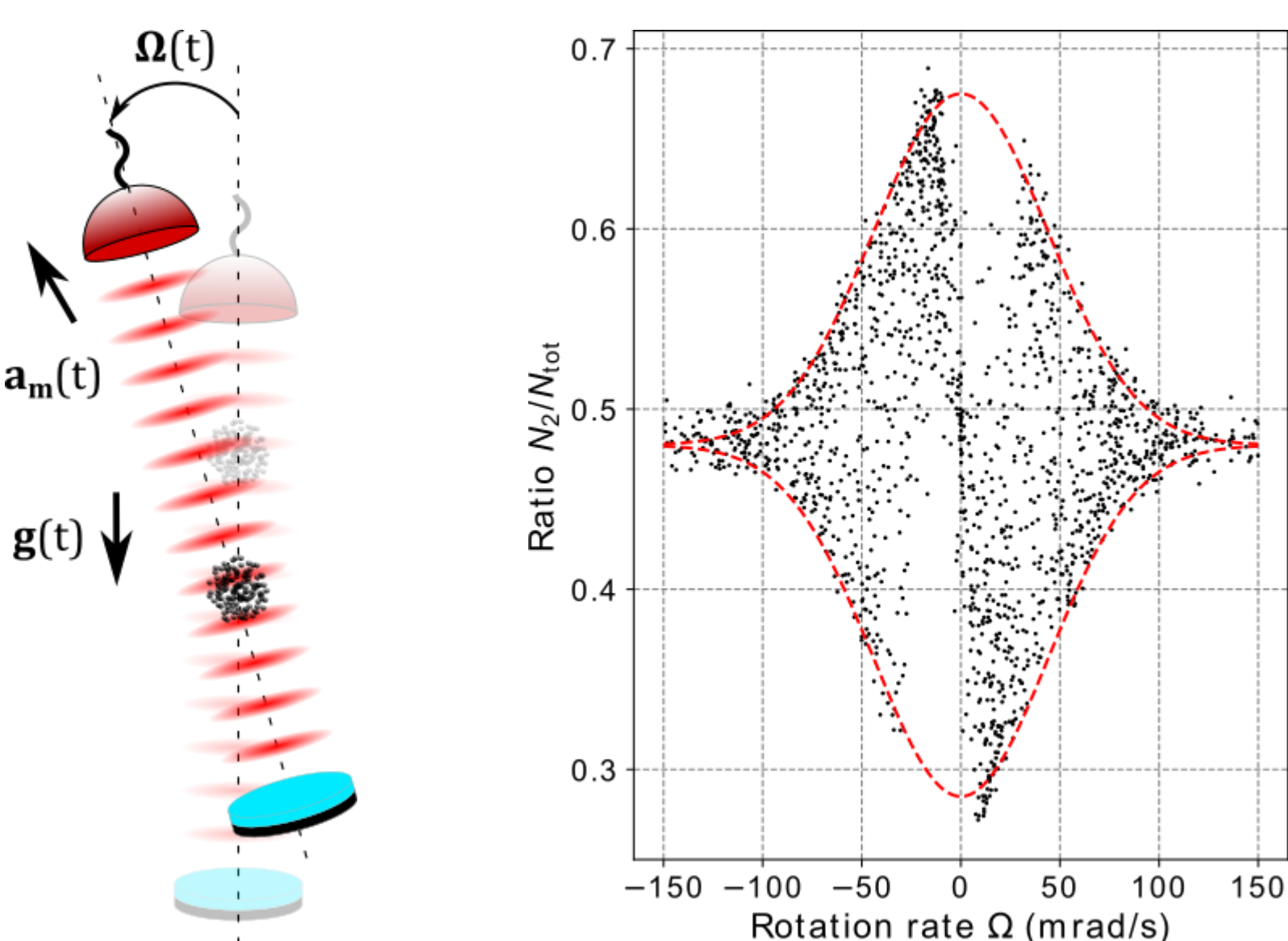


- Outcome:** recovery of the atomic interference pattern's full amplitude
- Stable value over the measured range $|\Omega| \leq 250$ mrad/s $\approx 14^\circ/s$
- Compatible with navigation applications



A more complex atomic trajectory in the mirror's rotating frame

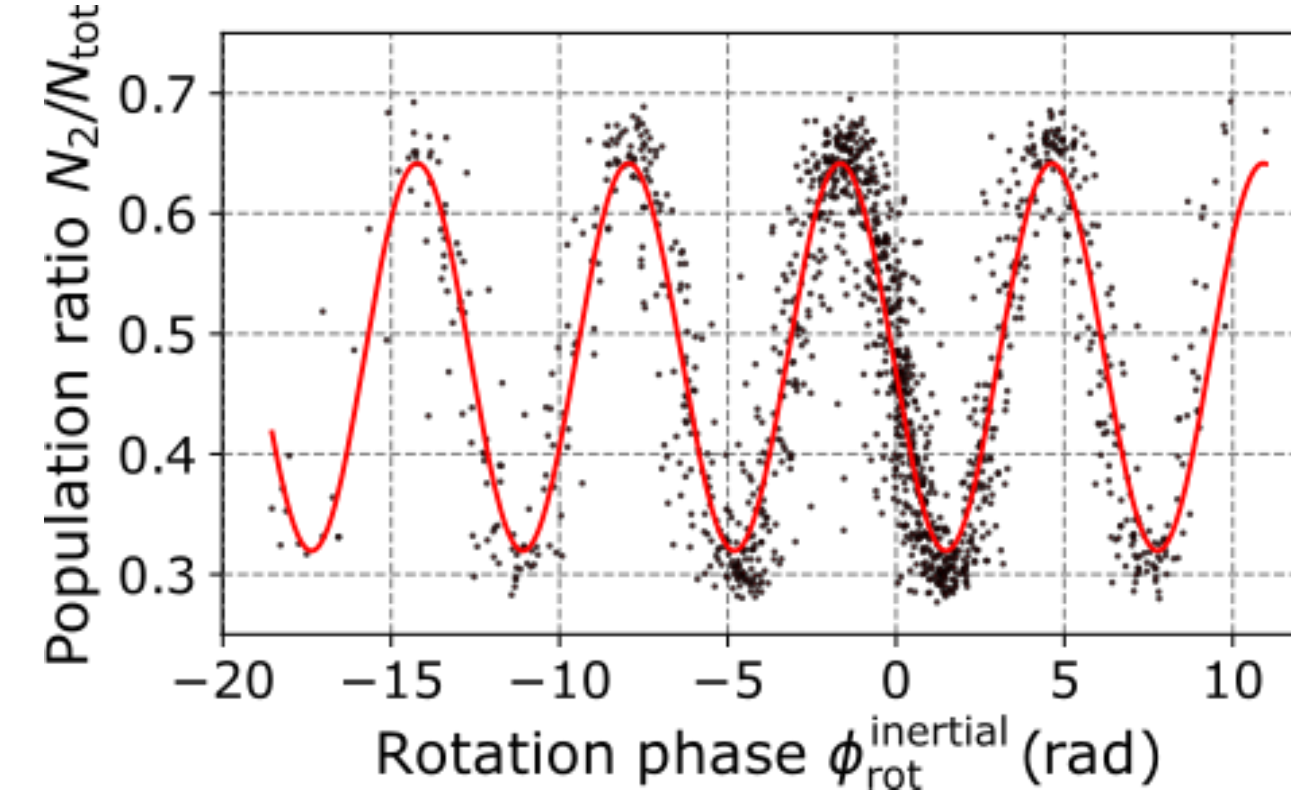
- Problem:** rotation-induced acceleration terms scrambling the atomic phase
- No information can be retrieved at the output of the atom interferometer



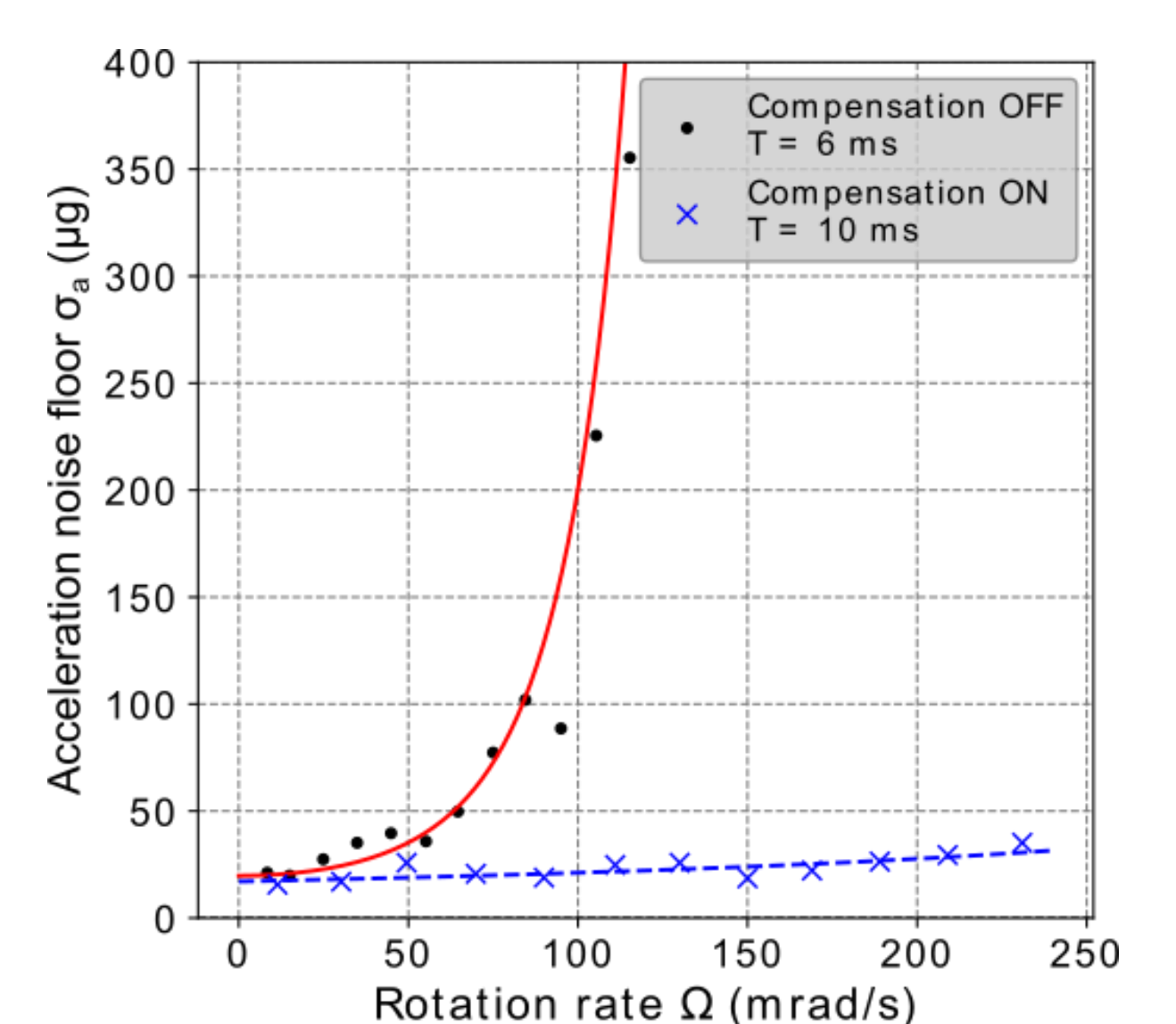
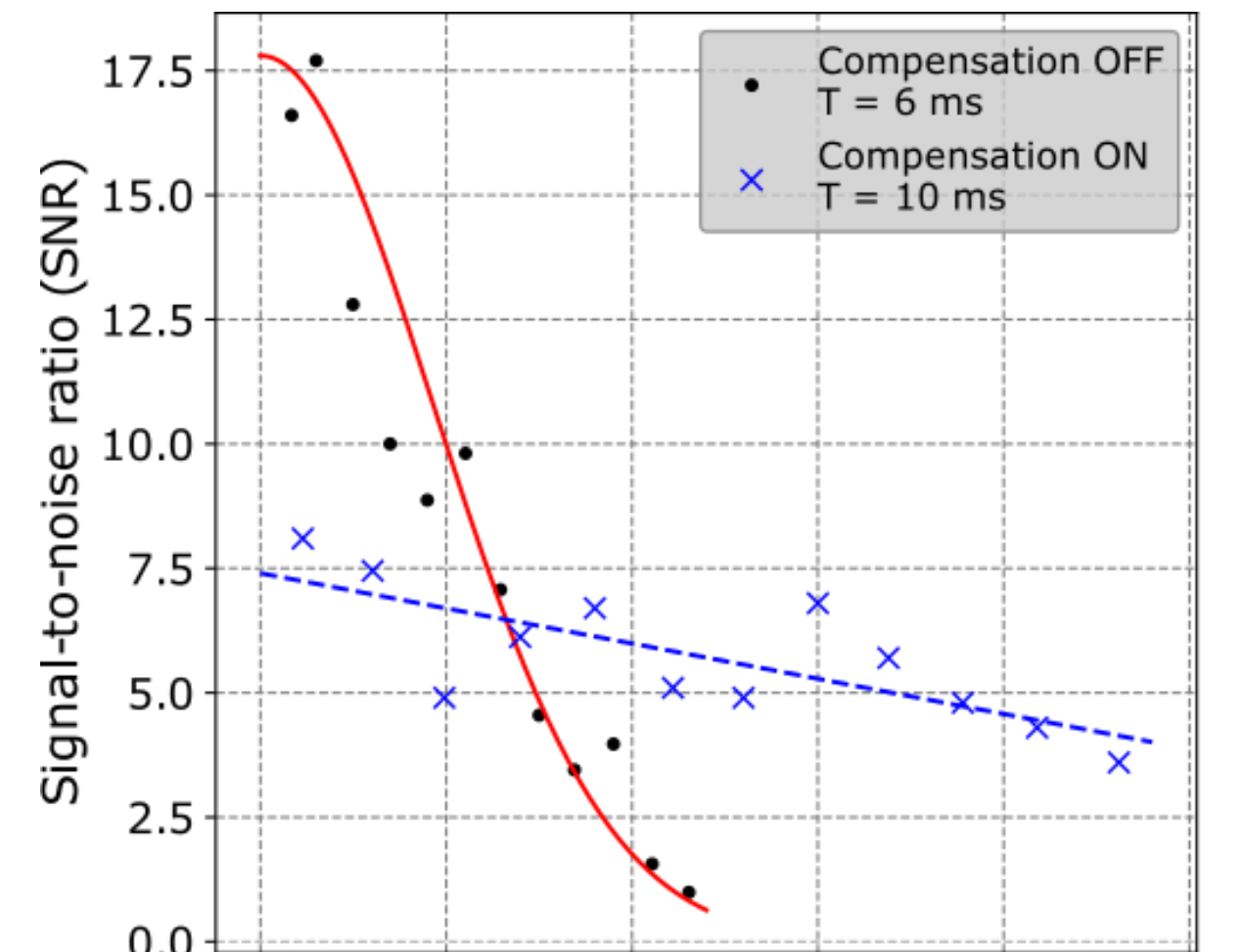
- Solution:** determination of the new equation of motion $\mathbf{a}(t) = \ddot{\mathbf{r}}(t) + 2[\boldsymbol{\Omega}(t) \times \dot{\mathbf{r}}(t)] + \boldsymbol{\Omega}(t) \times [\boldsymbol{\Omega}(t) \times \mathbf{r}(t)] + \dot{\boldsymbol{\Omega}}(t) \times \mathbf{r}(t)$
- Correction of the additional rotation-induced phase shift

Yielding a robust quantum inertial sensor operable at any arbitrary orientation and rotation rate [4]

- Wide operating range recovered $|\Omega| \leq 14^\circ/s$; $\theta \in [0, 30]^\circ$
- Signal-to-noise ratio at $T = 10$ ms $\text{SNR} = C(\Omega)/\sigma_\phi = 5.4$
- Corresponding accel. sensitivity $\bar{\sigma}_a = 23.6$ $\mu\text{g} \approx 2\sigma_a^{\text{static}}$



- Improved dynamic, compatible with navigation requirements
- Uncompensated performances limited by the contrast decay
- Compensated performances limited by the vibrations regime



References

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- Cheiney, P. et al. "Navigation-Compatible Hybrid Quantum Accelerometer Using a Kalman Filter", Phys. Rev. Applied **10**, 034030 (2018)
- Templier, S. et al. "Tracking the vector acceleration with a hybrid quantum accelerometer triad", Science Advances **8**, eadd3854 (2022)
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